NAG Toolbox for MATLAB

f07ue

1 Purpose

f07ue solves a real triangular system of linear equations with multiple right-hand sides, AX = B or $A^{T}X = B$, using packed storage.

2 Syntax

```
[b, info] = f07ue(uplo, trans, diag, ap, b, 'n', n, 'nrhs_p', nrhs_p)
```

3 Description

f07ue solves a real triangular system of linear equations AX = B or $A^{T}X = B$, using packed storage.

4 References

Golub G H and Van Loan C F 1996 Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J 1989 The accuracy of solutions to triangular systems SIAM J. Numer. Anal. 26 1252-1265

5 Parameters

5.1 Compulsory Input Parameters

1: uplo - string

Indicates whether A is upper or lower triangular.

$$uplo = 'U'$$

A is upper triangular.

$$uplo = 'L'$$

A is lower triangular.

Constraint: **uplo** = 'U' or 'L'.

2: trans – string

Indicates the form of the equations.

The equations are of the form AX = B.

$$trans = 'T' or 'C'$$

The equations are of the form $A^{T}X = B$.

Constraint: trans = 'N', 'T' or 'C'.

3: diag – string

Indicates whether A is a nonunit or unit triangular matrix.

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```
diag = 'N'
```

A is a nonunit triangular matrix.

diag = 'U'

A is a unit triangular matrix; the diagonal elements are not referenced and are assumed to be 1.

Constraint: diag = 'N' or 'U'.

4: ap(*) – double array

Note: the dimension of the array **ap** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$.

The n by n triangular matrix A, packed by columns.

More precisely,

if **uplo** = 'U', the upper triangle of A must be stored with element A_{ij} in $\mathbf{ap}(i+j(j-1)/2)$ for $i \le j$;

if **uplo** = 'L', the lower triangle of A must be stored with element A_{ij} in $\mathbf{ap}(i+(2n-j)(j-1)/2)$ for $i \ge j$.

If $\mathbf{diag} = '\mathbf{U}'$, the diagonal elements of A are assumed to be 1, and are not referenced; the same storage scheme is used whether $\mathbf{diag} = '\mathbf{N}'$ or 'U'.

5: b(ldb,*) - double array

The first dimension of the array **b** must be at least $max(1, \mathbf{n})$

The second dimension of the array must be at least $max(1, nrhs_p)$

The n by r right-hand side matrix B.

5.2 Optional Input Parameters

1: n - int32 scalar

Default: The first dimension of the array **ap** and the second dimension of the array **ap**. (An error is raised if these dimensions are not equal.)

n, the order of the matrix A.

Constraint: $\mathbf{n} \geq 0$.

2: nrhs_p - int32 scalar

Default: The second dimension of the array b.

r, the number of right-hand sides.

Constraint: **nrhs** $\mathbf{p} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

ldb

5.4 Output Parameters

1: b(ldb,*) - double array

The first dimension of the array **b** must be at least $max(1, \mathbf{n})$

The second dimension of the array must be at least max(1, nrhs_p)

The n by r solution matrix X.

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2: info - int32 scalar

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

info = -i

If info = -i, parameter i had an illegal value on entry. The parameters are numbered as follows:

1: uplo, 2: trans, 3: diag, 4: n, 5: nrhs_p, 6: ap, 7: b, 8: ldb, 9: info.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

info > 0

If **info** = i, a(i,i) is exactly zero; A is singular and the solution has not been computed.

7 Accuracy

The solutions of triangular systems of equations are usually computed to high accuracy. See Higham 1989.

For each right-hand side vector b, the computed solution x is the exact solution of a perturbed system of equations (A + E)x = b, where

$$|E| \le c(n)\epsilon |A|,$$

c(n) is a modest linear function of n, and ϵ is the *machine precision*.

If \hat{x} is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_{\infty}}{\|x\|_{\infty}} \le c(n)\operatorname{cond}(A, x)\epsilon, \quad \operatorname{provided} \quad c(n)\operatorname{cond}(A, x)\epsilon < 1,$$

where $cond(A, x) = ||A^{-1}||A||x||_{\infty}/||x||_{\infty}.$

Note that $\operatorname{cond}(A, x) \leq \operatorname{cond}(A) = \||A^{-1}||A|\|_{\infty} \leq \kappa_{\infty}(A)$; $\operatorname{cond}(A, x)$ can be much smaller than $\operatorname{cond}(A)$ and it is also possible for $\operatorname{cond}(A^{\mathrm{T}})$ to be much larger (or smaller) than $\operatorname{cond}(A)$.

Forward and backward error bounds can be computed by calling f07uh, and an estimate for $\kappa_{\infty}(A)$ can be obtained by calling f07ug with **norm_p** = 'I'.

8 Further Comments

The total number of floating-point operations is approximately n^2r .

The complex analogue of this function is f07us.

9 Example

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```
0.31;
0.070000000000000001;
      -8.02;
      -5.95;
      0.12];
b = [-12.9, -21.5;
16.75, 14.93;
-17.55, 6.33;

-11.04, 8.09];

[bOut, info] = f07ue(uplo, trans, diag, ap, b)
bOut =
   -3.0000
               -5.0000
   -1.0000
                1.0000
     2.0000
                -1.0000
     1.0000
                 6.0000
info =
              0
```

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